

RS-485 Transceiver with Fail -Safe

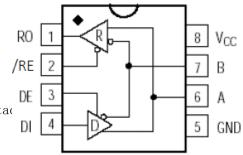
product description

BL1587 is a half-duplex RS-485 transceiver, the chip contains a driver and a receiver. BL1587 can provide the highest transfer rate of 2Mbps. The chip has a built-in fail-safe circuit to ensure that the output of the receiver is in a logic high state when the input of the receiver is open or short-circuited. The BL1587 has a 1/4 unit load receiver input impedance, allowing up to 128 transceivers on the bus.

Product Features

- ➤ +5V working voltage
- > Maximum transfer rate: 2Mbps
- > Built-in fail-safe circuit
- > Bus allows up to 128 transceivers
- ➤ I/O pin ESD protection: ± 15kV IEC 61000-4-2, contact
- > SOP8 package

Block Diagram



Application field

- > smart meter
- > industrial control
- security monitor

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Pin definition

| seri al numb er | name | function |
|--------------------------|------|--|
| 1 | RO | receiver output |
| 2 | /RE | Receiver output enable. RO output is valid when / RE is low level; RO is high impedance state when /RE is high level |
| 3 | DE | Driver output enable. The driver output is valid when DE is high level, and the output is high impedance state when DE is low level |
| 4 | DI | drive input |
| 5 | GND | grounding |
| 6 | А | Receiver non-inverting input and driver non-inverting output |
| 7 | В | Receiver inverting input and driver inverting output |
| 8 | V cc | power supply |

Driver Truth Table

| ente r | | | outp ut | | |
|-----------|----|----|---------------------|--------|--|
| /RE | DE | DI | А | В | |
| Х | 1 | 1 | 1 | 0 | |
| Х | 1 | 0 | 0 | 1 | |
| 0 | 0 | Х | High-Z | High-Z | |
| 1 | 0 | Х | Shutdown (High-Z) | | |

Receiver Truth Table

| | outp | | |
|-----|------|--------|----|
| r | | | ut |
| /RE | DE | AB | RO |
| 0 | X | >-50mV | 1 |

| 0 | X | <-200mV | 0 |
|---|---|-------------|---------------------|
| 0 | X | open /short | 1 |
| 1 | 1 | X | High-Z |
| 1 | 0 | X | Shutdown (High-Z) |



Limit parameter

| parameters | the symbol | limit value | unit |
|---------------------------------|-----------------|-------------------|------------|
| Operating Voltage | V _{cc} | +7 | V |
| Control input voltage | /RE, DE | -0.3 to V cc +0.3 | V |
| Driver input voltage | DI | -0.3 to V cc +0.3 | V |
| Driver output voltage | A, B | ±13 | V |
| Receiver input voltage | A, B | ±13 | V |
| Receiver output voltage | RO | -0.3 to V cc +0.3 | V |
| range of working temperature | | -40~+85 | $^{\circ}$ |

DC Electrical Characteristics

(VCC=+5 V \pm 5 % ,TA=-40 °C \sim +85 °C, typical value is at VCC=+5V, TA = 25 °C (Note 1)

| parameter | symbol | Test Conditions | minimu m value | typica l value | maximu m value | unit |
|--|------------------|---------------------------|----------------------|----------------------|----------------------|------|
| Operating Voltage | V _{cc} | | 4.5 | | 5.5 | V |
| driver | | | · | | | |
| Differential driver output (no | V _{OD1} | Figure 1 | | | V _{cc} | V |
| load) | | \\(\rm \) | | | | |
| Differential Driver Output | V_{OD2} | VCC=5V Figure 1, R=27Ω | 1.5 | 2.1 | | V |
| The magnitude of the differential output voltage | ΔV od | Figure 1, R=27Ω | | | 0.2 | V |
| Variation (Note 2 | | | | | | |
| Driver Common Mode Output Voltage | VOC _ | Figure 1, $R=27\Omega$ | 1.0 | | 3.0 | V |
| Amplitude variation of common mode | ΔV oc | Figure 1, R=27Ω | | | 0.2 | V |
| voltage | | | | | | |
| (Note 2) | | | | | | |
| input high voltage | V _ | DE,DI,/RE | 2.0 | | | V |

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| input low voltage | VIL | DE,DI,/RE | | | | 0.8 | V |
|------------------------|------------------|----------------|----------------------|------|------|-----|------------|
| DI input hysteresis | V _{HYS} | | | | 100 | | mV |
| Input Current (A | ı | DE=GND V cc | V _{IN} =12V | | | 220 | μA |
| , B) | IN4 | =GND | V _{IN} =-7V | -120 | | | P 2 |
| | | or 5.25V | | | | | |
| Driver short | I _{OSD} | A Pin Sho | rt to B Pin | -100 | | 100 | mA |
| circuit output | | | | | | | |
| current | | | | | | | |
| receiver | | | | | | | |
| Receiver | VTH _ | -7V ≤ VC | CM ≤ 12V _ | -200 | -125 | -50 | mV |
| Differential | _ | | | | | | |
| Threshold Voltage | | | | | | | |

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| Receiver Input Hysteresis | △ V тн | | | | 40 | | mV |
|---|-------------------|--|---------|-----|-----|-----|----|
| Receiver output high voltage | V _{OH} | I _O =-8mA, V 50mV | ID =- | 4.0 | | | V |
| Receiver output low voltage | V _{OL} | I _O =8mA,V _{II} 200mV |)=- | | | 0.4 | V |
| Receiver Tri-State Output Current | QUR _ | | | | | ±1 | μΑ |
| Receiver input impedance | R _{IN} | -7V ≤ VCM | ≤ 12V _ | 48 | | | ΚΩ |
| Receiver output short circuit current | OSR_ | 0V ≪ V _{RO} ≤ | € V cc | ±7 | | ±95 | mA |
| supply current | | | | | | | |
| _ | | | DE=V cc | | 900 | | μΑ |
| supply current | CC | /RE=DI= GND or _{VCC} | DE=GND | | 900 | | μΑ |
| Standby Mode Supply Current | I _{SHDN} | DE=GND, /F | | | | 10 | μΑ |

Note 1: All currents into the device are positive and all currents out of the device are negative; all voltages are to ground unless otherwise specified. Note 2: When DI input changes state, \triangle V op and \triangle V oc V op and V oc amount of change.

transmission characteristics

(VCC=+5V±5%, TA=-40 $^{\circ}$ $^{\circ}$ +85 $^{\circ}$, the typical value is VCC=+5V , TA = 25 $^{\circ}$)

| parameter | symbol | cond itio n | minimu m value | typica 1 value | maximu m value | unit |
|---|-----------------------------------|---|----------------------|----------------------|----------------------|------|
| Driver input | wxya _ | Figures 3 and 5, R DIFF | | 13 | | 20 |
| to output | t _{DPHL} | =54Ω C _{L1} =C _{L2} =100pF | | 17 | | ns |
| delay | | | | | | |
| Driver output delay difference Toplh - Tophl | tDSKEW - | Figures 3 and 5, R _{DIFF} =54Ω C _{L1} =C _{L2} =100pF | | 5 | | ns |
| Driver Rise or Fall Time | t _{DR} , t _{DF} | Figures 3 and 5, R DIFF = 54Ω C $_{L1}$ = C $_{L2}$ = 100 pF | | 8 | | ns |
| maximum rate | F _{MAX} | | 2 | | | Mbps |

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| Driver Enable to Output High | wxya _ | Figure 4 6, C L=100pF S2 and Closed | 20 | ns |
|---|------------------------------|---|----|----|
| Driver Enable to Input low level | wxya _ | Figure 4 6, C _L =100pF S1 and Closed | 28 | ns |
| drives the output low from the to off time | lm _w | Figure 4 6, C _L =15pFS1 and Closed | 19 | ns |
| drives the output high from the to off time | wxya _ | Figure 4 6, C _L =15pF S2 and Closed | 16 | ns |
| Receiver input and output Delay | t _{RPLH} tRPHL _ | 7 and 9, _ | 42 | ns |

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| | | ; rise and fall time of VID \leq 15ns | | |
|---|------------------------|---|------|----|
| T _{RPLH} - T _{RPHL} | t _{RSKD} | 7 and 9, _ | 5 | ns |
| Difference between | | ; rise and fall time of VID ≦ 15ns | | |
| receiver input and output | | | | |
| delay | | | | |
| Receiver Enable to Input | wxya _ | Figure 2 8, C _{RL} =15pF S1 and Closed | 10 | ns |
| out low | | Ciosed | | |
| Receiver Enable to Input | wxya _ | Figure 2 8, C _{RL} =15pF S2 and Closed | 45 | ns |
| high | | | | |
| receiver outputs low from the | lm _w | Figure 2 8, C _{RL} =15pF S1 and Closed | 10 | ns |
| to shutdown Receiver | | Figure 2 8, C _{RL} =15pF S2 | | |
| output high from | wxya _ | and Closed | 45 | ns |
| to shutdown circuit off time | t _{SHDN} | | 100 | ns |
| Driver Enable from Standby to Output High | t _{DZH(SHDN)} | Figures 4 and 6, C _L =100pF S2 Closed | 1600 | ns |
| from standby to output low driver enable | t _{DZL(SHDN)} | Figure 4 6, C L=100pF S1 and Closed | 1600 | ns |
| Receiver Enable from Standby to | t _{RZH(SHDN)} | Figure 2 8, C _{RL} =15pF S2 and Closed | 1500 | ns |
| Output High | | | | |
| Receiver Enable from Standby to | t _{RZL(SHDN)} | Figure 2 8, C _{RL} =15pF S1 and Closed | 2300 | ns |
| Output Low | | | | |



test circuit

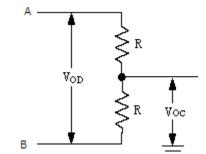


Figure 1: Driver DC Test Load

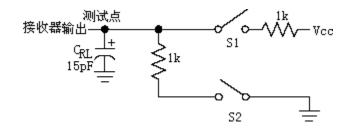


Figure 2: Receiver Enable/Disable Timing Testload



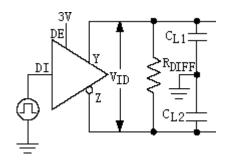


图 3: Driver Timing Test Circuit

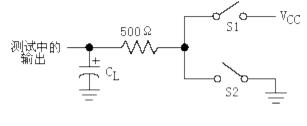


图 4: Driver Enable/Disable Timing Test Load

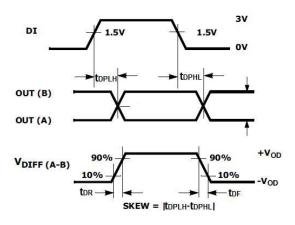


图 5: Driver Propagation Delays

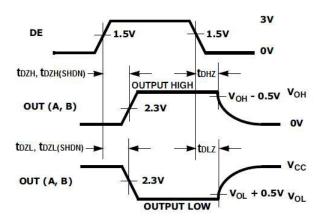
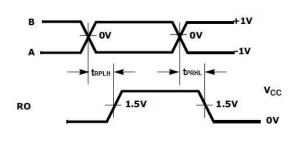


图 6: Driver Enable and Disable Times



 $\label{eq:Figure 7} \textit{Figure 7}: \ \textit{Receiver Propagation Delays}$

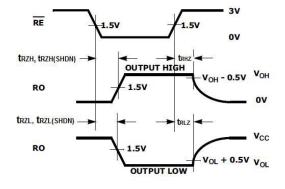


Figure 8: Receiver Enable and Disable Times

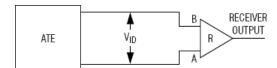


Figure 9: Receiver Propagation Delay Test Circuit

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Typical Application Diagram

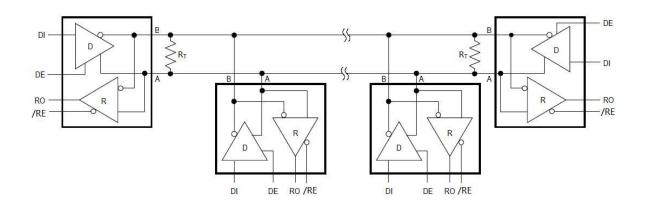
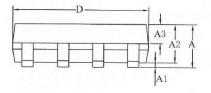


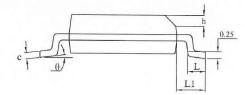
Figure 10 Typical half-duplex RS-485 network

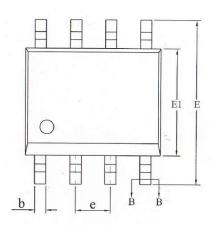
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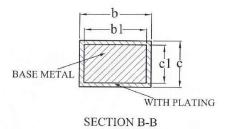


Package size (SOP8)









| SYMBOL | MILLIMETER | | | |
|--------|------------|---------|------|--|
| SIMBOL | MIN | NOM | MAX | |
| A | _ | _ | 1.77 | |
| A1 | 0.08 | 0.18 | 0.28 | |
| A2 | 1.20 | 1.40 | 1.60 | |
| A3 | 0.55 | 0.65 | 0.75 | |
| b | 0.39 | - | 0.48 | |
| b1 | 0.38 | 0.41 | 0.44 | |
| с | 0.20 | I | 0.26 | |
| c1 | 0.19 | 0.20 | 0.21 | |
| D | 4.70 | 4.90 | 5.10 | |
| Е | 5.80 | 6.00 | 6.20 | |
| E1 | 3.70 | 3.90 | 4.10 | |
| e | | 1.27BSC | | |
| h | 0.25 | _ | 0.50 | |
| L | 0.50 | | 0.80 | |
| L1 | | 1.05REF | | |
| θ | 0 | | 8° | |