

## With fail-safe function ( Fail-Safe ), low power consumption, limited slew rate

### RS-485 transceiver

#### product description

BL1585B is a 5V power supply, half-duplex RS-485 transceiver, the chip contains a driver and a receiver. The BL1585B uses a slew-rate-limited driver, which can significantly reduce EMI and reflections caused by improperly terminated cables, and realize

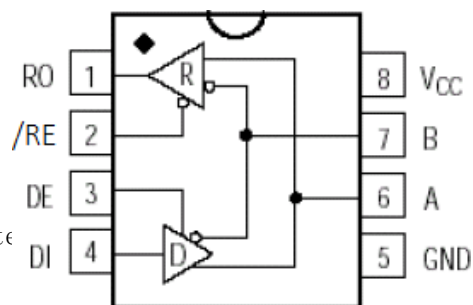
Now up to 500kbps error-free data transmission. BL1585B has a built-in fail-safe circuit to ensure that the output of the receiver is in a logic high state when the input of the receiver is open or short-circuited.

BL1585B receiver is 1/8 unit load, allowing up to 256 transceivers to be connected to the bus to realize half-duplex communication. BL1585B I/O pins have  $\pm 15\text{kV}$  IEC 61000-4-2 contact discharge protection capability.

#### Product Features

- +5V working voltage
- Built-in fail-safe circuit
- Up to 500kbps transfer rate
- Allows up to 256 transceivers on the bus
- With  $\pm 15\text{kV}$  IEC 61000-4-2 Contact discharge protection
- SOP8 package

#### Block Diagram



#### Application field

- smart meter
- industrial control
- security monitor



### Pin definition

| serial number | name            | function  |
|---------------|-----------------|---|
| 1             | RO              | receiver output   |
| 2             | /RE             | Receiver output enable. RO output is valid when /RE is low level; RO is high impedance state when /RE is high level                 |
| 3             | DE              | Driver output enable. The driver output is valid when DE is high level, and the output is high impedance state when DE is low level |
| 4             | DI              | drive input   |
| 5             | GND             | grounding   |
| 6             | A               | Receiver non-inverting input and driver non-inverting output  |
| 7             | B               | Receiver inverting input and driver inverting output  |
| 8             | V <sub>CC</sub> | power supply  |

#### Driver Truth Table

| enter |    |    | output              |        |
|-------|----|----|---------------------|--------|
| /RE   | DE | DI | A                   | B      |
| x     | 1  | 1  | 1                   | 0      |
| x     | 1  | 0  | 0                   | 1      |
| 0     | 0  | x  | High-Z              | High-Z |
| 1     | 0  | x  | Shutdown ( High-Z ) |        |

#### Receiver value-added table

| enter |    |         | output |
|-------|----|---------|--------|
| /RE   | DE | AB      | RO     |
| 0     | x  | >-50mV  | 1      |
| 0     | x  | <-200mV | 0      |

|   |   |              |                     |
|---|---|--------------|---------------------|
| 0 | x | open / short | 1                   |
| 1 | 1 | x            | High-Z              |
| 1 | 0 | x            | Shutdown ( High-Z ) |

### Limit parameter

| parameters              | the symbol | limit value          | unit |
|-------------------------|------------|----------------------|------|
| Operating Voltage       | $V_{CC}$   | +7                   | V    |
| Control input voltage   | /RE, DE    | -0.3 to $V_{CC}+0.3$ | V    |
| Driver input voltage    | DI         | -0.3 to $V_{CC}+0.3$ | V    |
| Driver output voltage   | A, B       | -8~+13               | V    |
| Receiver input voltage  | A, B       | -8~+13               | V    |
| Receiver output voltage | RO         | -0.3 to $V_{CC}+0.3$ | V    |

### temperature range

|                       |             |
|-----------------------|-------------|
| Operating temperature | -40~+85 °C  |
| storage temperature   | -65~+150 °C |

### DC Electrical Characteristics

(  $V_{CC} = +5V \pm 5\%$  ,  $T_A = -40^{\circ}C \sim +85^{\circ}C$  , typical value at  $V_{CC} = +5V$  ,  $T_A = 25^{\circ}C$  )(Note 1)

| parameter   | symbol          | Test Conditions        | minimum value | typical value | maximum value | unit |
|---|-----------------|------------------------|---------------|---------------|---------------|------|
| Operating Voltage   | $V_{CC}$        |                        | 4.5           |               | 5.5           | V    |
| <b>driver</b>   |                 |                        |               |               |               |      |
| Differential driver output (no load)                                | $V_{OD1}$       | Figure 1               |               |               | 5             | V    |
| Differential Driver Output  | $V_{OD2}$       | Figure 1, $R=27\Omega$ | 1.5           |               |               | V    |
| The magnitude of the differential output voltage Variation (Note 2) | $\Delta V_{OD}$ | Figure 1, $R=27\Omega$ |               |               | 0.2           | V    |

|   |                  |                 |     |  |     |   |
|---|------------------|-----------------|-----|--|-----|---|
| Driver Common Mode Output Voltage                   | VOC <sub>-</sub> | Figure 1, R=27Ω | 1.0 |  | 3.0 | V |
| Amplitude variation of common mode voltage (Note 2) | ΔV <sub>oc</sub> | Figure 1, R=27Ω |     |  | 0.2 | V |
| input high voltage                                  | V <sub>-</sub>   | DE,DI,/RE       | 2.0 |  |     | V |
| input low voltage                                   | VI <sub>L-</sub> | DE,DI,/RE       |     |  | 0.8 | V |

|   |                 |   |                    |         |      |          |            |
|---|-----------------|---|--------------------|---------|------|----------|------------|
| DI input hysteresis                     | $V_{HYS}$       |   |                    | 100     |      | mV       |            |
| Input Current ( A , B )                 | $I_{IN4}$       | DE=GND                                      | $V_{IN}=12V$       |         | 125  | $\mu A$  |            |
|   |                 | $V_{CC}=GND$<br>or 5.25V                    | $V_{IN}=-7V$       | -75     |      |          |            |
| Driver short circuit output current     | $I_{OSD}$       | $-7V \leq V_{OUT} \leq V_{CC}$              |                    | -100    |      | mA       |            |
|   |                 | $0V \leq V_{OUT} \leq 12V$                  |                    |         | 100  |          |            |
| <b>receiver</b>                         |                 |   |                    |         |      |          |            |
| Receiver Differential Threshold Voltage | $V_{TH\_}$      | $-7V \leq V_{CM} \leq 12V\_$                |                    | -200    | -125 | -50      | mV         |
| Receiver Input Hysteresis               | $\Delta V_{TH}$ |   |                    |         | 40   |          | mV         |
| Receiver output high voltage            | $V_{OH}$        | $I_O=-8mA, V_{ID}=-50mV$                    |                    | 4.0     |      |          | V          |
| Receiver output low voltage             | $V_{OL}$        | $I_O=8mA, V_{ID}=-200mV$                    |                    |         |      | 0.4      | V          |
| Receiver Tri-State Output Current       | $QUR\_$         |   |                    |         |      | $\pm 1$  | $\mu A$    |
| Receiver input impedance                | $R_{IN}$        | $-7V \leq V_{CM} \leq 12V\_$                |                    | 96      |      |          | K $\Omega$ |
| Receiver output short circuit current   | $OSR\_$         | $0V \leq V_{RO} \leq V_{CC}$                |                    | $\pm 7$ |      | $\pm 95$ | mA         |
| <b>supply current</b>                   |                 |   |                    |         |      |          |            |
| supply current                          | $I_{CC}$        | No load , /RE=DI=GND or VCC                 | DE=V <sub>CC</sub> |         | 150  | 600      | $\mu A$    |
|   |                 |   | DE=GND             |         | 185  | 600      | $\mu A$    |
| Standby Mode Supply Current             | $I_{SHDN}$      | DE=GND, /RE=VCC , DI=V <sub>CC</sub> or GND |                    |         |      | 10       | $\mu A$    |

Note 1 : All currents into the device are positive and all currents out of the device are negative; all voltages are to ground unless otherwise specified. Note 2 : When DI input changes state,  $\Delta V_{ob}$  and  $\Delta V_{oc}$   $V_{ob\_}$  and  $V_{oc}$  amount of change.

## transmission characteristics

(  $V_{CC}=+5V\pm 5\%$ ,  $T_A=-40^\circ C \sim +85^\circ C$  , the typical value is  $V_{CC}=+5V$  ,  $T_A = 25^\circ C$  )

| parameter | symbol | cond itio | minimu m | typica l | maximu m | unit |
|-----------|--------|-----------|----------|----------|----------|------|
|-----------|--------|-----------|----------|----------|----------|------|

|   |                                   | n  | value | value | value |      |
|---|-----------------------------------|--|-------|-------|-------|------|
| Driver input to output delay                              | wxya _                            | Figures 3 and 5, $R_{DIFF} = 54\Omega$ $C_{L1} = C_{L2} = 100pF$ |       | 450   | 800   | ns   |
|   | t <sub>DPHL</sub>                 |  |       | 450   | 800   |      |
| Driver output delay difference<br>$ T_{DPLH} - T_{DPLH} $ | tDSKEW _                          | Figures 3 and 5, $R_{DIFF} = 54\Omega$ $C_{L1} = C_{L2} = 100pF$ |       |       | 100   | ns   |
| Driver Rise or Fall Time                                  | t <sub>DR</sub> , t <sub>DF</sub> | Figures 3 and 5, $R_{DIFF} = 54\Omega$ $C_{L1} = C_{L2} = 100pF$ |       | 150   | 500   | ns   |
| maximum rate  | F <sub>MAX</sub>                  |  | 500   |       |       | kbps |



|   |  |   |  |     |     |    |
|---|--|---|--|-----|-----|----|
| Driver Enable to Output High  | wxya <sub>-</sub>                      | Figures 4 and 6, C <sub>L</sub> =100pF S2<br>Closed         |  |     | 200 | ns |
| Driver Enable to Input low level  | wxya <sub>-</sub>                      | Figures 4 and 6, C <sub>L</sub> =100pF S1<br>Closed         |  |     | 200 | ns |
| drives the output low from the to off time  | Im <sub>w</sub>                        | Figures 4 and 6, C <sub>L</sub> =15pF S1<br>Closed          |  |     | 300 | ns |
| drives the output high from the to off time   | wxya <sub>-</sub>                      | Figures 4 and 6, C <sub>L</sub> =15pF S2<br>Closed          |  |     | 300 | ns |
| Receiver input and output delay   | t <sub>RPLH</sub><br>t <sub>RPHL</sub> | 7 and 9, <sub>-</sub><br>; rise and fall time of VID ≅ 15ns |  | 450 | 800 | ns |
| T <sub>RPLH</sub> - T <sub>RPHL</sub>  <br>Difference between receiver input and output delay | t <sub>RSKD</sub>                      | 7 and 9, <sub>-</sub><br>; rise and fall time of VID ≅ 15ns |  | 30  |     | ns |
| Receiver Enable to Input out low  | wxya <sub>-</sub>                      | Figures 2 and 8, C <sub>RL</sub> =15pF S1<br>Closed         |  | 20  | 50  | ns |
| Receiver Enable to Input high   | wxya <sub>-</sub>                      | Figures 2 and 8, C <sub>RL</sub> =15pF S2<br>Closed         |  | 20  | 50  | ns |
| receiver outputs low from the to shutdown   | Im <sub>w</sub>                        | Figures 2 and 8, C <sub>RL</sub> =15pF S1<br>Closed         |  | 80  | 150 | ns |
| Receiver output high from to shutdown   | wxya <sub>-</sub>                      | Figures 2 and 8, C <sub>RL</sub> =15pF S2<br>Closed         |  | 80  | 150 | ns |
| circuit off time  | t <sub>SHDN</sub>                      |   |  | 50  | 300 | ns |
| Driver Enable from Standby  | t <sub>DZH(SHDN)</sub>                 | Figures 4 and 6, C <sub>L</sub> =100pF S2                   |  |     | 200 | ns |

|   |                 |   |  |  |     |    |
|---|-----------------|---|--|--|-----|----|
| to Output High                              |                 | Closed  |  |  |     |    |
| from standby to output low driver enable    | $t_{DZL(SHDN)}$ | Figures 4 and 6, $C_L = 100pF$ S1<br>Closed   |  |  | 200 | ns |
| Receiver Enable from Standby to Output High | $t_{RZH(SHDN)}$ | Figures 2 and 8, $C_{RL} = 15pF$ S2<br>Closed |  |  | 300 | ns |
| Receiver Enable from Standby to Output Low  | $t_{RZL(SHDN)}$ | Figures 2 and 8, $C_{RL} = 15pF$ S1<br>Closed |  |  | 300 | ns |

test circuit

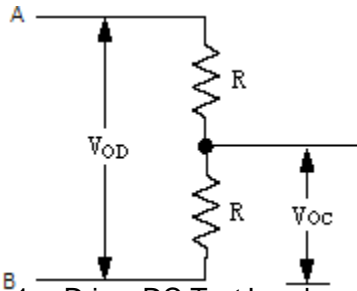


Figure 1: Driver DC Test Load

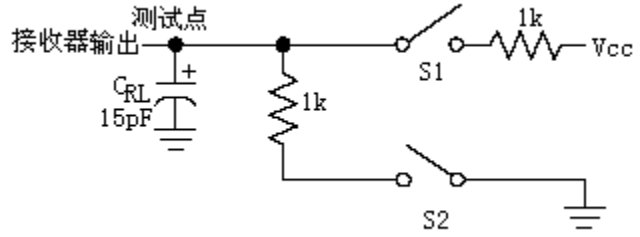


Figure 2: Receiver Enable/Disable Timing Testload

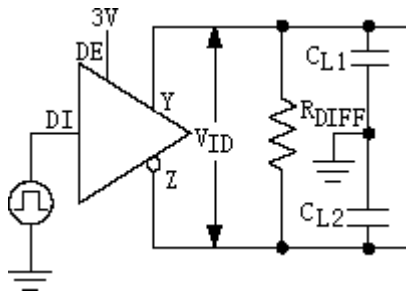


图 3: Driver Timing Test Circuit

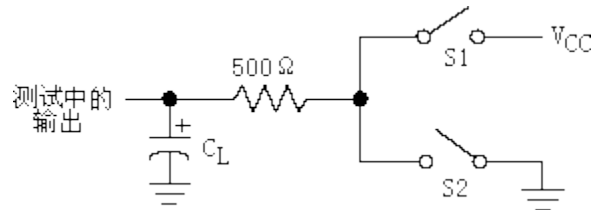


图 4: Driver Enable/Disable Timing Test Load

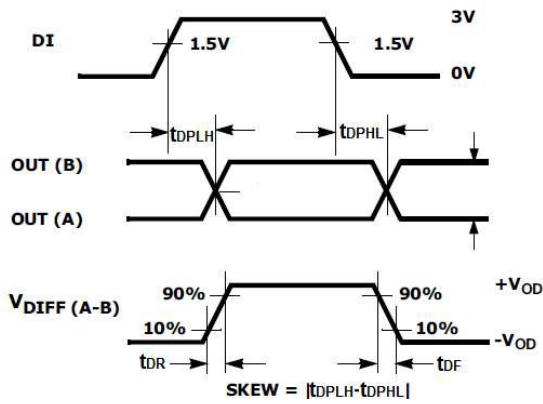


图 5: Driver Propagation Delays

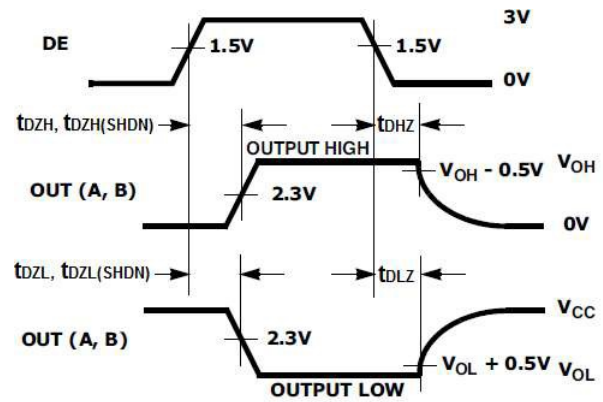


图 6: Driver Enable and Disable Times

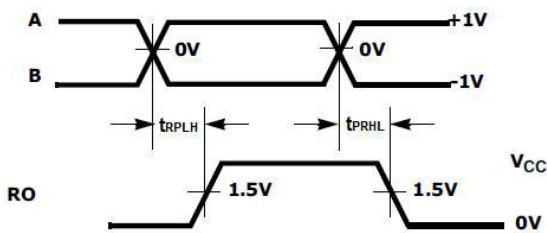


Figure 7: Receiver Propagation Delays

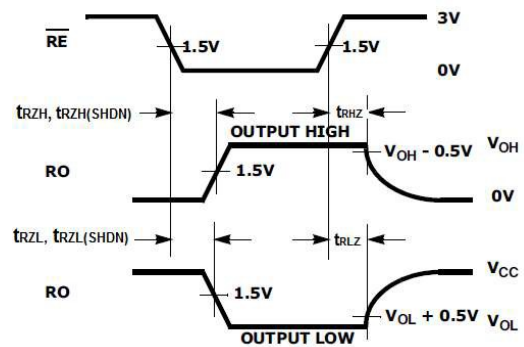


Figure 8: Receiver Enable and Disable Times

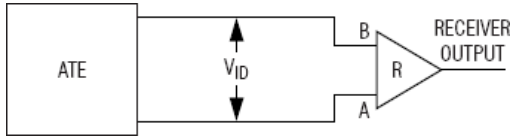


Figure 9 : Receiver Propagation Delay Test Circuit

**Typical Application Diagram**

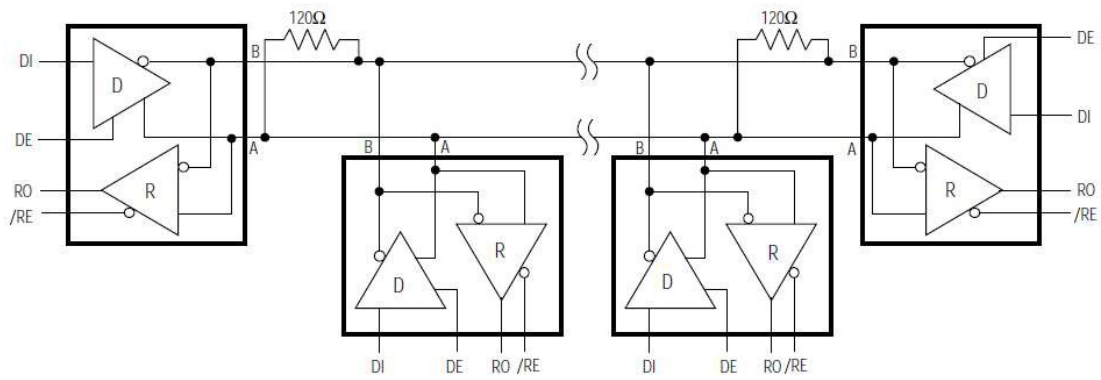
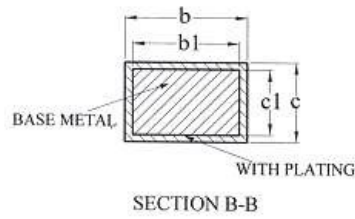
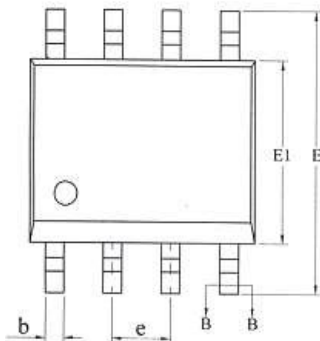
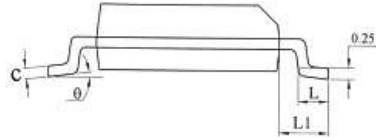
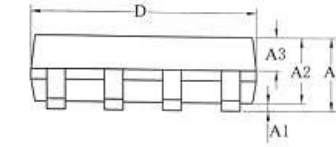


Figure 10 Typical half-duplex RS-485 network

## Package size (SOP8)



| SYMBOL | MILLIMETER |      |      |
|--------|------------|------|------|
|        | MIN        | NOM  | MAX  |
| A      | —          | —    | 1.77 |
| A1     | 0.08       | 0.18 | 0.28 |
| A2     | 1.20       | 1.40 | 1.60 |
| A3     | 0.55       | 0.65 | 0.75 |
| b      | 0.39       | —    | 0.48 |
| b1     | 0.38       | 0.41 | 0.43 |
| c      | 0.21       | —    | 0.26 |
| c1     | 0.19       | 0.20 | 0.21 |
| D      | 4.70       | 4.90 | 5.10 |
| E      | 5.80       | 6.00 | 6.20 |
| E1     | 3.70       | 3.90 | 4.10 |
| e      | 1.27BSC    |      |      |
| L      | 0.50       | 0.65 | 0.80 |
| L1     | 1.05BSC    |      |      |
| 0      | 0          | —    | 8°   |